User's Manual

For

ESS17-04 / ESS17-07

Integrated Stpper Motor

©2020 All Rights ReservedAttention: Please read this manual carefully before using the Motor!







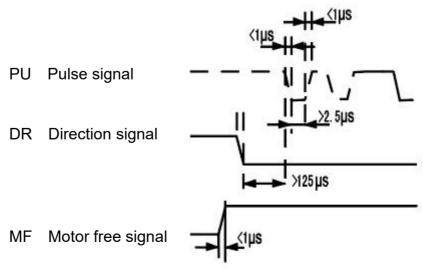
ESS17-04 / ESS17-07

Integrated Stepper Motor

Features

- Using a new 32-bit motor control, dedicated DSP chip
- Pulse input frequency up to 200 KHz
- Small torque attenuation, speed up to 3000 RPM
- Built-in alarm output, for monitoring and controlling
- Intelligently adjust current, reduce vibration, noise and this can increase efficiency by 35%
- Pulse/direction (PU / DR) control
- Default microstep resolution: 1000
- Voltage range: DC24V ~ 36V
- Over-voltage, under-voltage and over-current protection
- Excellent high speed performance and rigidity, combined with advantages of servo motor and stepper motor
- Drive and motor integrated, simple wiring

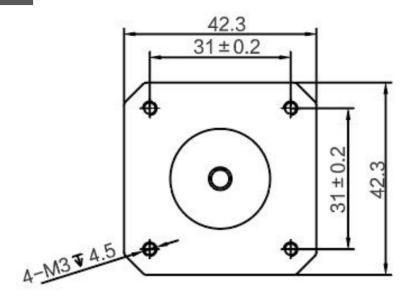
Input signal waveform sequence diagram



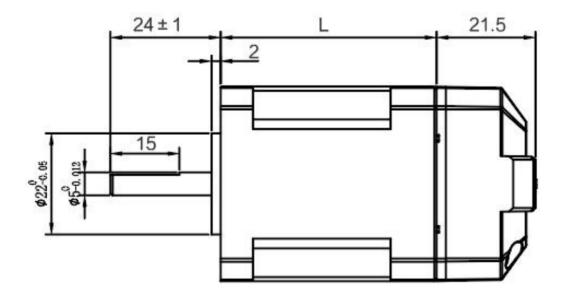


Installation size (unit: mm)

Front view

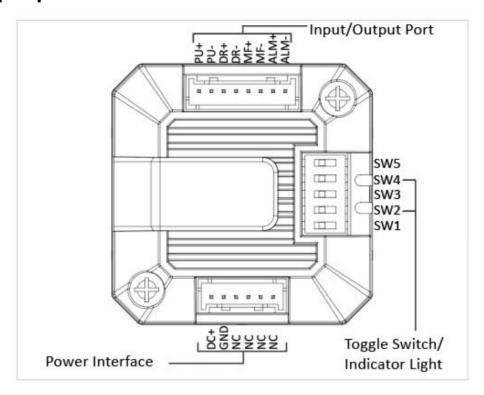


Side view





Input/output ports



| Function | Specification | Remark | |
|----------|-------------------------|--|--|
| VDC+ | Supply voltage | VDC: 24V ~ 36V | |
| GND | Ground | VDC. 24V ~ 36V | |
| PU+ | Pulse input signal+ | | |
| PU- | Pulse input signal- | | |
| DR+ | Direction input signal+ | Signal power supply: 5V ~ 24V, | |
| DR- | Direction input signal- | >5V, add a current-limiting resistance | |
| MF+ | Motor freed signal+ | | |
| MF- | Motor freed signal- | | |
| ALM+ | Alarm output signal+ | Over-current, over-voltage, position following err | |
| ALM- | Alarm output signal- | alarm output | |
| - | NC | NC | |



Toggle Switch description

| PU/Rev | SW2 | SW3 | SW4 | SW5 |
|--------|-----|-----|-----|-----|
| 400 | ON | ON | ON | ON |
| 800 | OFF | ON | ON | ON |
| 1600 | ON | OFF | ON | ON |
| 3200 | OFF | OFF | ON | ON |
| 6400 | ON | ON | OFF | ON |
| 12800 | OFF | ON | OFF | ON |
| 25600 | ON | OFF | OFF | ON |
| 51200 | OFF | OFF | OFF | ON |
| 1000 | ON | ON | ON | OFF |
| 2000 | OFF | ON | ON | OFF |
| 4000 | ON | OFF | ON | OFF |
| 5000 | OFF | OFF | ON | OFF |
| 8000 | ON | ON | OFF | OFF |
| 10000 | OFF | ON | OFF | OFF |
| 20000 | ON | OFF | OFF | OFF |
| 40000 | OFF | OFF | OFF | OFF |

SW1: Motor rotation direction OFF=CW , ON=CCW

Electrical Specifications

| Parameters | ESS17-04 / ESS17-07 | | | |
|-----------------------|---------------------|-----|-----|------|
| rarameters | MIN | TYP | MAX | UNIT |
| Output Current | 0 | - | 2 | A |
| Input Voltage | 18 | 24 | 36 | Vdc |
| Logic Signal Current | 7 | 10 | 16 | mA |
| Logic Signal Voltage | - | 5 | 24 | V |
| Pulse Input Frequency | 0 | - | 200 | kHz |
| Isolation Resistance | 100 | - | - | ΜΩ |



Others Specifications

| Parameters | UNIT | ESS17-04 | ESS17-07 |
|-----------------------|-------|----------|----------|
| NO. of Phase | | 2 | 2 |
| Step Angle | ٥ | 1.8 | 1.8 |
| Motor length | mm | 47 | 60 |
| Holding Torque | N.m | 0.48 | 0.75 |
| Rated Current | А | 2.0 | 2.0 |
| Resistance/Phase | Ω | 1.35 | 1.80 |
| Inducatance/Phase | mH | 2.9 | 3.7 |
| Rotor Inertia | g.cm2 | 77 | 110 |
| Weight | Kg | 0.43 | 0.53 |
| Insulation Class | | В | |
| Operating Temperature | °c | 0 ~ 55 | |

Fault diagnosis

| Fault code | Fault Information | RUN / ALM Output | Reset |
|------------|------------------------------|------------------|-------------------------------|
| Err1:0x01 | Over-current / short circuit | | Power down reset |
| Err2:0x02 | Over-voltage | | Lock machine /auto recoery |
| Err3:0x03 | Under-voltage | | Lock machine /auto recoery |
| Err5:0x05 | position following error | | Power down reset |



Operating Environment

| Cooling | Natual cooling | | |
|---------------------|----------------|---|--|
| | Workplace | Stay away from other heating sources, Avoid dust, oil fog , corrosive and combustible gases and Strong vibration site | |
| Working Environment | Temperature | 0°c ~ 50°c | |
| | Humidity | 40 - 90%RH(no condensation, no frosting) | |
| | Vibration | 10 ~ 55Hz/0.15mm | |
| Storage Temperature | -20°c ~ +80°c | | |

Marning:

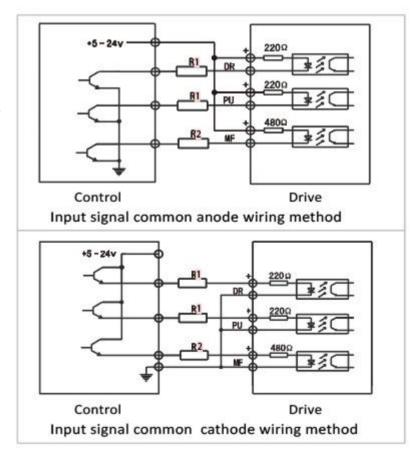
Motor installation, do not knock motor back cover, so as to avoid damage encoder.

Control signal connection

+5V: R1=0, R2=0

+12V: R1=510 Ω , R2=820 Ω

+24V: R1=1.2KΩ, R2=1.8KΩ





Control signal connection(Output singal)

